

MITSUBISHI HIGH SPEED CMOS

M74HC123P/FP/DP

DUAL RETRIGGERABLE MONOSTABLE MULTIVIBRATOR

DESCRIPTION

The M74HC123 is a semiconductor integrated circuit consisting of two retriggerable monostable multivibrators with direct reset inputs.

FEATURES

- Retriggerable multivibrator can generate wide output pulses.
- Direct reset input can interrupt output pulses.
- High-speed: 28ns typ. (C_L=15pF, V_{CC}=5V)
- Low power dissipation: 20µW/package, max (V_{CC}=5V, T_a=25°C, quiescent state)
- High noise margin: 30% of V_{CC}, min (V_{CC}=4.5V, 6V)
- Capable of driving 10 74LSTTL loads
- Wide supply voltage range: V_{CC}=2~6V
- Wide operating temperature range: T_a=−40~+85°C

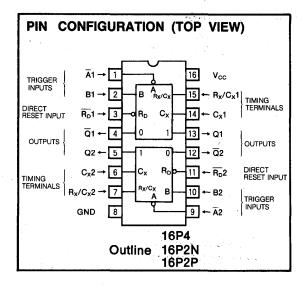
APPLICATION

General purpose, for use in industrial and consumer digital equipment.

FUNCTIONAL DESCRIPTION

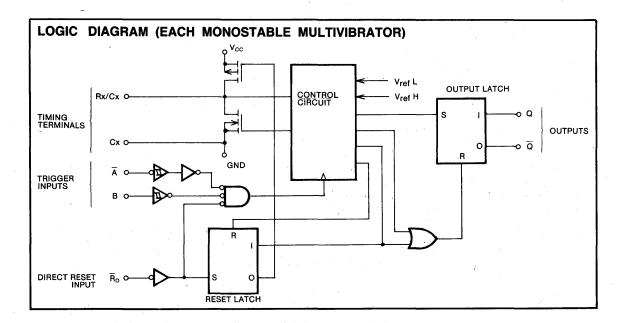
Use of silicon gate technology allows the M74HC123 to maintain the low power dissipation and high noise margin characteristics of the standard CMOS logic 4000B series while giving high-speed performance equivalent to the 74LS123.

When external resistor R_X and electrostatic capacitor C_X are connected to timing terminals R_X/C_X and C_X as shown in Fig. 1, and trigger pulses are applied at inputs \overline{A} or B, positive pulses will appear at Q and negative pulses at \overline{Q} . (Fig. 2-(a))



The pulse width t_{WQ} is set by R_X and C_X . The trigger is applied when \overline{A} changes from high-level to low-level or when B changes from low-level to high-level. The retrigger function is used to obtain longer pulse width and output pulses can be extended by retriggering at \overline{A} or B before the output pulse is completed. (Fig. 2-(b))

When direct reset input \overline{R}_D is set low, Q will be reset low and \overline{Q} will be reset high, irrespective of the output state, allowing output pulses to be narrower by \overline{R}_D . (Fig. 2-(c)) When \overline{R}_D changes from low-level to high-level while A is low and B is high, the trigger is applied and Q and \overline{Q} change state.





FUNCTION TABLE (Note 1)

-	Inputs		Out	puts
R₀	Ā	В	Q	ā
L	×	Х .	L	н
х	Н	×	L	н
X	х	L	L	н
Н	L	1	Л	П
Н	ţ	Н	Л	IJ
†		Н		7.

Note 1:

- † : Change from low to high level
- ↓ : Change from high to low level
- ☐: Positive one-shot operation
- X: Irrelevant

OPERATION

1. How to use the timing terminals

Resistor R_X and capacitor C_X are connected to timing terminals R_X/C_X and C_X , as shown in Fig. 1. If C_X is polar, the positive lead should be connected to the R_X/C_X side, and the negative lead to the C_X side. A diode is connected to prevent latchup.

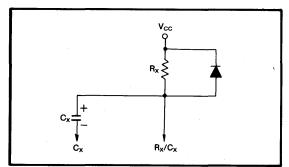


Fig.1 Connection of external resistor R_X and capacitor C_X to timing terminals R_X/C_X and C_X

2. Output Pulse Width t_{WQ}

The output pulse width t_{WQ} is determined as follows: When $C_X>100000pF$, $R_X\geqq10k\Omega$ $t_{WQ}=0.46C_X\cdot R_X$ (ns) C_X is given in pF, and R_X in $k\Omega$.

3. Output Pulse Width Control

The output pulse width can be controlled in the following three ways.

3-1 Normal Use

Fig. 2-(a) is the directions as ordinary monostable multivibrator operation and the output pulse width t_{WQ} can be set by using the formula and figure shown in section 2 above.

3-2 Extendtion of the output pulse width with retrigger function

As shown in Fig. 2-(b), the output pulse width can be extended at will by applying additional trigger pulses before the output is completed.

3–3 Shortening of the output pulse width with $\overline{R_D}$ signal As shown in Fig. 2-(c), the output pulse which has been generated by the trigger signal can be terminated with the $\overline{R_D}$ signal and it is possible to shorten its width as reguired.

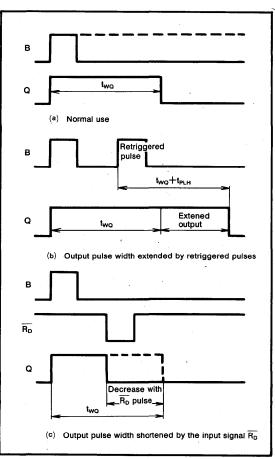


Fig.2 Output pulse width control

4. Precations for Use

- 4-1 Additional trigger pulses must be applied at least trr later after the previous trigger pulse has been applied. The retrigger pulse during this period is ineffective.
- $4\!-\!2$ The lead length of external resistor R_X and capacitor C_X should be as short as possible (less than 3cm) to minimize stray wiring capacitance and to prevent misoperation due to noise. Care should also be taken to isolate this circuit from noise sources as far as possible.
- 4-3 $\,$ Insert a capacitor of $0.01\sim0.1\mu F$ with good high-frequency characteristics between V_{CC} and GND.
- 4-4 Output pulses may be generated when the power is switched on.
- $4-5\,$ Capacitor discharge when the power is turned off may cause thermal breakdown or latchup, so a diode should be connected as shown in Fig. 1.

ABSOLUTE MAXIMUM RATINGS $(T_a = -40 \sim +85 ^{\circ}C$, unless otherwise noted)

Symbol	Parameter	Conditions	Ratings	Unit
Vcc	Supply voltage		-0.5~+7.0	V
Vi	Input voltage		-0.5~V _{cc} +0.5	V
Vo	Output voltage		-0.5~V _{cc} +0.5	V
	Input protection diode current	V ₁ < 0V	-20	
lık .	input protection diode current	V _i > V _{cc}	20	mA
	Output paralitie diede current	V ₀ < 0V	-20	
lok	Output parasitic diode current	Vo > Vcc	20	mA
lo	Output current, per output pin		±25	mA
Icc	Supply/GND current	V _{CC} , GND	±50	mA
Pd	Power dissipation	(Note 2)	500	mW
Tstg	Storage temperature range		−65~ + 150	င

Note 2 : M74HC123FP, T $_a$ = $-40\sim+70$ °C and T $_a$ = $70\sim85$ °C are derated at -6mW/°C. M74HC123DP, T $_a$ = $-40\sim+50$ °C and T $_a$ = $50\sim85$ °C are derated at -5mW/°C.

RECOMMENDED OPERATING CONDITIONS $(T_a = -40 \sim +85^{\circ}C)$

Symbol	Baua			Limits				
Зупівої	Parameter		Min	Тур	Max	Unit		
Vcc	Supply voltage	2		6	٧			
Vı	Input voltage		0		Vcc	٧		
V _o	Output voltage	0		Vcc	٧			
Topr	Operating temperature ran	40		+85	ဗ			
	Input risetime, falltime (A,	n	no restriction					
	Input risetime, falltime (RD)	$V_{CC} = 2.0V$	0		1000			
t _r , t _f		V _{CC} = 4.5V	0		500	ns		
		V _{CC} = 6.0V	0		400	1		
ь	Eutornal timing registeres	V _{CC} =2.0V	5		1000	1.0		
Rx	External timing resistance V _{CC} ≥3.0V		1		1000	kΩ		
C _x	External timing capacitance	е	n	no restriction				

M74HC123P/FP/DP

DUAL RETRIGGERABLE MONOSTABLE MULTIVIBRATOR

ELECTRICAL CHARACTERISTICS

					Limits					
Symbol	Parameter	Test	Test conditions		25℃			-40~+85℃		Unit
		V _{cc} (V)		Min	Тур	Max	Min	Max		
		$V_{O} = 0.1V, V_{CC} = 0.1V$ $ I_{O} = 20\mu A$		2.0	1.5			1.5		V
VIH	High-level input voltage			4.5	3.15			3. 15		
				6.0	4.2			4.2		
		$V_0 = 0.1V, V_{CC} = 0.1V$		2.0	, , ,		0.5		0.5	
VIL	Low-level input voltage			4.5			1.35		1.35	v
	$ I_0 = 20\mu A$		6.0			1.8	<u> </u>	1.8		
			$I_{OH} = -20\mu A$	2.0	1.9			1.9		
	High-level output voltage		$I_{OH} = -20\mu A$	4.5	4.4			4.4		
V _{OH}		$V_i = V_{iH}, V_{tL}$	$I_{OH} = -20\mu A$	6.0	5.9			5.9		v
			$I_{OH} = -4.0 \text{mA}$	4.5	4.18			4. 13		1
			$I_{OH} = -5.2 \text{mA}$	6.0	5. 68			5. 63		
			$I_{OL} = 20 \mu A$	2.0			0.1		0.1	
			$I_{OL} = 20 \mu A$	4.5			0.1		0.1	
VoL	Low-level output voltage	$V_{i} = V_{iH}, V_{iL}$	$I_{OL} = 20 \mu A$	6.0			0.1	ļ	0.1	V
			I _{OL} = 4.0mA	4.5			0.26		0, 33	
			I _{OL} = 5. 2mA	6.0			0.26		0.33	
I _{IH}	High-level input current (A, B, RD)	V _I == 6V		6, 0			0. 1		1.0	μA
I _{IL}	Low-level input current (A, B, RD)	$V_1 = 0V$		6.0			0.1		-1.0	μА
I _{IH}	High-level input current (R _X /C _X)	$V_1 = 6V$		6.0			0.5		5.0	
I _{IL}	Low-level input current (R _X /C _X)	$V_i = 0V$		6.0			-0.5		-5.0	μА
Icc	Quiescent supply current	VI = VCC, GNE	$I_0 = 0 \mu A$	6.0			4.0		40.0	μA
				2.0			120		160	
· loc	Active supply current	$V_i = V_{CC}$, GND, $R_X/C_X = 0.5V_{CC}$		4.5	-		300		400	μA
				6.0	}		600		800	l

SWITCHING CHARACTERISTICS $(V_{CC} = 5V, T_a = 25^{\circ}C)$

Symbol	Parameter	Test conditions		Unit		
	raiametei	rest conditions	Min	Тур	Max	Unit
t _{TLH}	Low-level to high-level and high-level to low-level				10	ns
t _{THL}	output transition time				10	ns
t _{PLH}	Low-level to high-level and high-level to low-level				43	ns
t _{PHL}	output propagation time (A, B-Q, Q)	0 -15-5 (N-4-4)			43	ns
t _{PLH}	Low-level to high-level and high-level to low-level	C _L =15pF (Note 4)			46	ns
t _{PHL}	output propagation time (Trigger input)($\overline{R_D}$ - Q , \overline{Q})				46	ns
t _{PLH}	Low-level to high-level and high-level to low-level				35	ns
t _{PHL}	output propagation time (Reset input)(RD-Q, Q)				35	ns

SWITCHING CHARACTERISTICS ($V_{cc} = 2\sim6V$, $T_a = -40\sim+85$ °C)

	Borometer			Limits 40 Losso					
Symbol	Parameter	Test conditions			25℃		-40~+85°C		Unit
			V _{cc} (V)	Min	Тур	Max	Min	Max	
			2.0			- 75		95	}
t _{TLH}	Low-level to high-level and		4.5			15		19	ns
	high-level to low-level		6.0			13]	16	
	Ingli-level to low-level	· ·	2.0			75		95	
t _{THL} output trans	output transition time		4.5			15	· .	19	ns
		1.	6.0			13	ŀ	16	
			2.0			240		300	
t _{PLH}	Low-level to high-level and		4.5			48		60	ns
	high-level to low-level		6.0			41		51	
	output propagation time	` ·	2.0			240		300	
t _{PHL}	(Ā, B-Q, Q)		4.5			48		60	ns
			6.0			41	-	51	
		C _L = 50pF (Note 4)	2.0			265		330	
t _{PLH} high-lev	Low-level to high-level and		4.5	i		53		66	ns
	high-level to low-level		6.0			45		55	
output propagation time	·	2.0			265		330		
t _{PHL}	(Trigger input)		4.5	<u> </u>		53		66	ns
	$(\overline{R_D}-Q,\overline{Q})$		6.0			45		55	
			2.0			195		245	
t _{PLH}	Low-level to high-level and		4.5			39		49	ns
	high-level to low-level		6.0			33	1	42	
	output propagation time	İ	2.0			195		245	
tpHL	(Reset input)		4.5			39	l	49	l ns
	$(\overline{R}_{D}-Q,\overline{Q})$		6.0	1		33		42	1
	Pulse width difference		 ,			 	t -	<u>-</u>	
Δt_{WQ}	between circuits in								%
-110	the same package]	,				1
		C _X =0pF (Note 4)	2.0	-	 	1000		1250	
two	Minimum output pulse	$R_X=5k\Omega$ (V _{CC} =2V)	4.5		'	200	,	250	ns
(MIN)	width	$R_X=1k\Omega$ (V _{CC} =4.5, 6V)	6.0			180		230	
		C _x =100pF	2.0	47	1.	67		67	
		$R_X=10k\Omega$	4.5	47		57		57	με
		C _L =50pF (Note 4)	6.0	47		57		57	~``
twa	Output pulse width	C _X =0.1μF	2.0	0.42	-	0.54	0.42	0.50	
		$R_x=10k\Omega$	4.5	0.42	-	0.50	0.42	0.50	ms
		C _L =50pF (Note 4)	6.0	0.42		0.50	0.42	0.50	'''
C ₁	Input capacitance	C Copi (Note 1)		0. 72		10	0. 72	10	pF
C _{PD}	Power dissipation capacitance (Note 3	n .		<u> </u>		+ 10			pF

Note 3: C_{PD} is the internal capacitance of the IC calculated from operation supply current under no-load conditions. The power dissipated during operation under no-load conditions is calculated using the following formula: $P_D = C_{PD} \cdot v_{CC}^2 \cdot f_1 + I_{CC} \cdot v_{CC}$

TIMING REQUIERMENTS ($v_{cc} = 2\sim 6v$, $T_a = -40\sim +85^{\circ}C$)

		• .			Limits					
Symbol	Parameter	Test conditions		25℃			-40~+85°C		Unit	
			V _{cc} (V)	Min	Тур	Max	Min	Max		
	T		2.0			100		120		
tw Minimum trigger pulse		4.5			20		24	ns		
(Ā, B)	width		6.0			17		21		
			2.0			75		90		
t _w	Minimum direct reset	1	4.5	1	1	15	}	18	ns	
(R _D)	pulse width		6.0	-	1	13		16		
		C _X =100pF	4.5							
trr		R _X =1kΩ	6.0						ns	
	Minimum retrigger time	C _X =0.1µF	4.5						-	
		R _X =1kΩ	6.0						ns	



